# Rotoreraft

# Wision

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#### Features of the Future World Environment

- High time value for travelers and goods
- Demand for rapid, reliable transport
- Increasing urban/suburban land value
- Demand for routine access to remote areas
- Requirements for robust military systems
- Opportunities for advanced technologies



## The Transportation Dilemma

#### ☐ Road transport is no longer a candidate

- Requires valuable land in urban areas
- High capital cost
- Not a high-speed or long-distance solution
- Adverse environmental impact



#### ☐ Rail offers just a partial solution

- Inflexible routes, high capital cost, topographical constraints
- Cost effective only at high traffic densities
- Competes with other uses for land

#### ☐ Fixed-wing air capacity is severely limited by need for runways

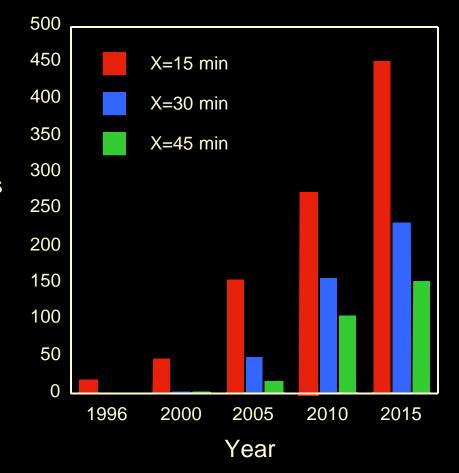
- Runway capacity is the bottleneck
- New runways are costly, require valuable land, raise environmental concerns, and have long lead times
- Urban and suburban airports (DCA, LGA, SFO, SJC, MIA, LAX, etc.) will be under great pressure to relocate



## Flight Delays Will Worsen Without Corrective Action

Predicted Delay Increase at a Major Hub Airport Based on MITRE DPAT Model

Number of Aircraft
Delayed by
More Than X Minutes



Single day, good weather Single airport, major hub

Total landings

1996: 997

2000: 1,378

2005: 1,576

2010: 1,776

2015: 1,910



#### **Future Rotorcraft Vision**

A mix of <u>vertical lift air vehicles</u>

operating within a <u>three-dimensional grid</u>

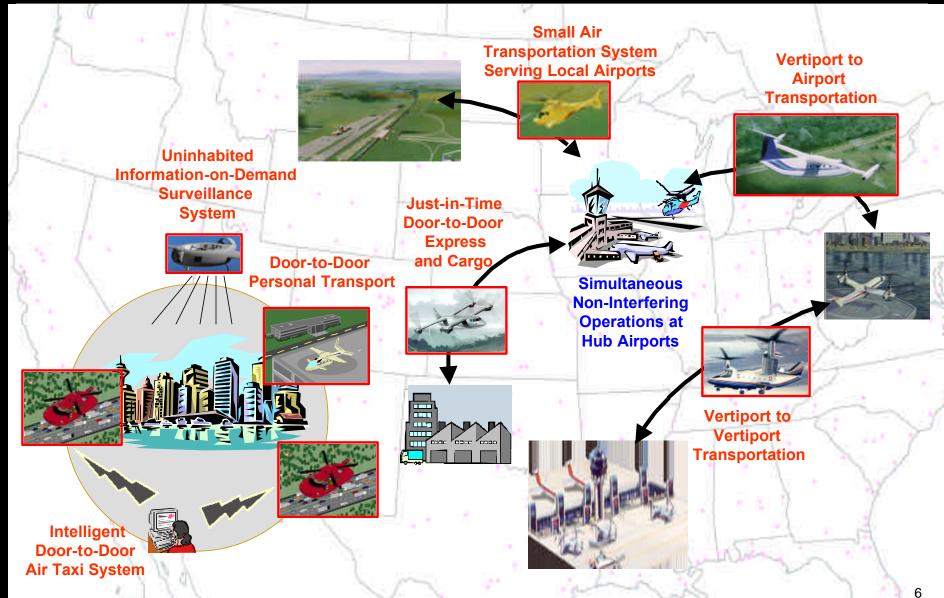
will <u>revolutionize</u> air transportation mobility:

- ✓ True point-to-point or door-to-door transport
- Complete flexibility of origin and destination
- ✓ No need for extensive real estate or large infrastructure investment
- No constraints on system throughput dictated by the need for runways





## Rotorcraft Vision





#### Runway Independent Aircraft Operations



Increases airport throughput by 25% and reduces delays at airports

Provides 50% as much delay reduction as a new runway

Improves terminal area airspace safety and reliability

- Separate corridors and runway traffic for slower aircraft and jet transports
- Improved separation in departure corridors

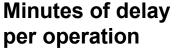


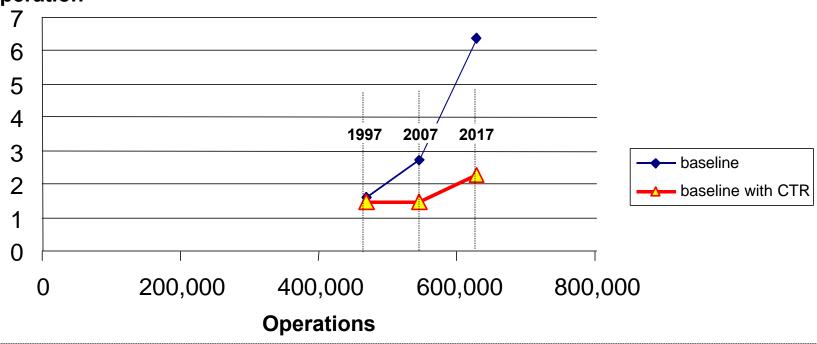
Commuter fixed wing aircraft (< 300 nm) carry 20% of the passengers, yet account for 40% of the departures at major hub airports



## Benefit of Runway Independent Operations

## Projected Operations and Delay at EWR 1997 to 2017







# Runway-Independent Rotorcraft Can Increase System Throughput by 25% or More

Eliminating runway use for short-haul travel increases capacity by 25%



Simultaneous Non-Interfering Operations for trips under 300 miles enable 30% throughput increase at hubs that account for 80% of traffic



#### AVSTAR

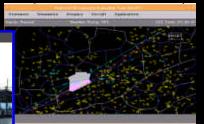
#### (Aviation Systems Technology Advanced Research)

Enabling Tomorrow's Air Transportation
System

Reduce separation in the terminal area

Remove restrictions across facility/sector boundaries

Improved traffic flow management



National
Traffic Flow
Management

**Integrated Airspace Decision Support Tools** 

Eliminate surface congestion

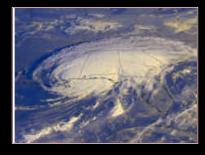


Runway Productivity

**Surface Congestion Alleviation** 

**Arrival/Departure Decision Support Tools** 



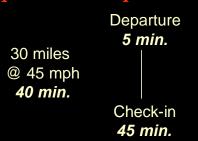


ATM/TFM Weather Integration



## Rotorcraft Can Sharply Reduce Door-to-Door Time

#### Airport to Airport (Fixed Wing)



200 miles @ 400 mph 30 min.

**Approach** & landing 5 min. Mode change 20 min.

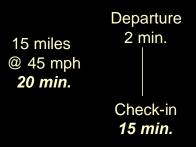
30 miles @ 45 mph

40 min.

#### Total trip time

200 miles: 185 min. 300 miles: 200 min. + Delay

#### GA Airport/Vertiport to GA Airport/Vertiport (Helicopter)



200 miles @ 200 mph 60 min.

Approach & landing 3 min. Mode change 10 min.

15 miles @ 45 mph 20 min.

15 miles

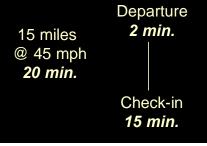
@ 45 mph

20 min.

Total trip time

200 miles: 130 min. 300 miles: 160 min.

#### GA Airport/Vertiport to GA Airport/Vertiport (Tiltrotor)



200 miles @ 300 mph 40 min.

Approach & landing 3 min.

Mode change 10 min.

#### Total trip time

200 miles: 110 min. 300 miles: 130 min.



## Barriers to Achieving the Vision

#### Key Inhibitors to Expanded Rotorcraft Applications:

- Cost per Seat-Mile or Ton-Mile
- Community Acceptance
- Reliable All-Weather Service
- Perceived Safety
- Passenger Acceptance (Ride Comfort, Speed, etc.)
- Piloting Skill Required
- Infrastructure for 3-D Grid Operation



### **Effects of Technology Improvement**

U.S. Army Future Transport Rotorcraft 20-ton Payload, 300-mile Mission Radius

<u> 1994</u>

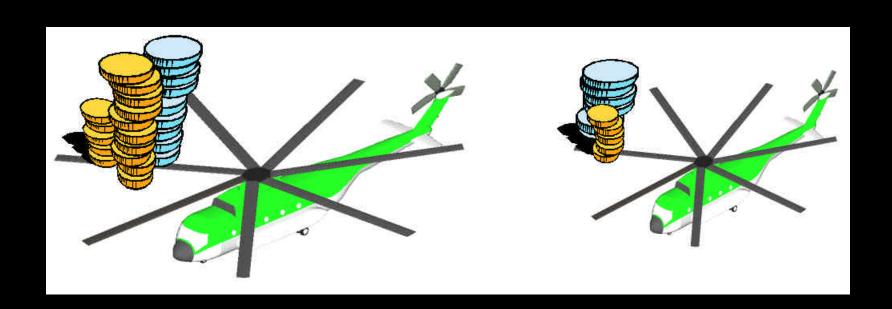
**Gross Weight:** 126 tons

Unit Flyaway Cost: \$186 mil.

**2005** 

62 tons (-51%)

\$74 mil. (-61%)



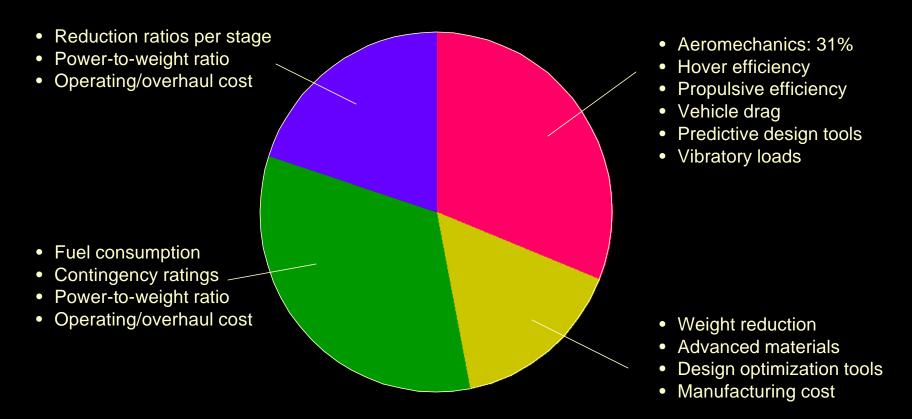


### Effects of Technology Improvement

#### **Future Transport Helicopter**

Percent gross weight/cost reduction by source

1994 - 2005





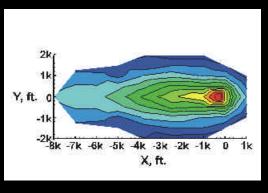
#### Tiltrotor Noise Reduction Breakthroughs

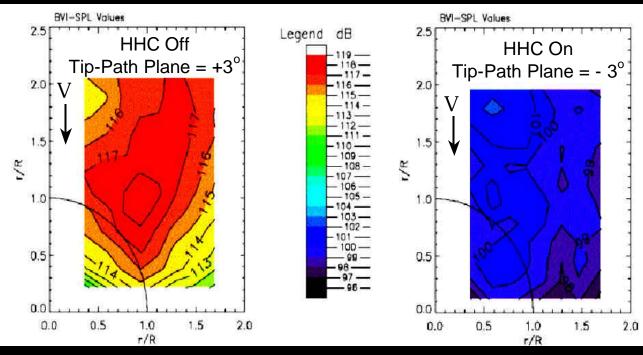
Typical reductions of 12.5 dB demonstrated in wind tunnel tests



Low-noise approach profiles reduce noise footprint

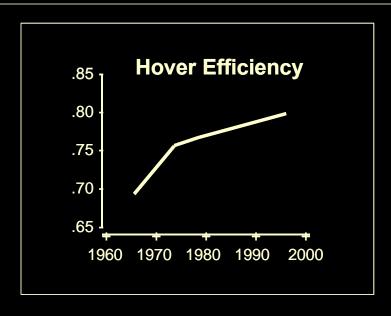


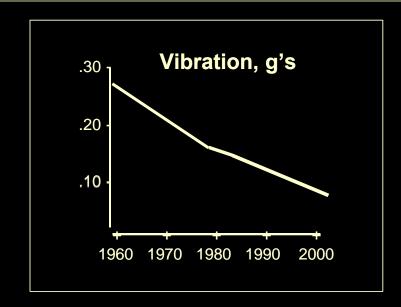


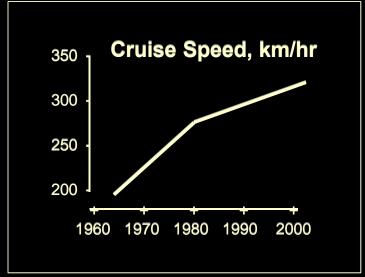


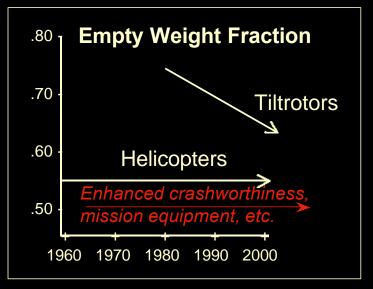


## Rotorcraft Technology Trends











## Long-Range Technology Goals

ATTRIBUTE	CURRENT LEVEL	2022 TARGET	
Vehicle Efficiency	Hover Efficiency = 0.78	0.87	
	L/D x Prop. Efficiency = 7 at V <sub>cruise</sub>	13 at V <sub>cruise</sub>	
	EW Fraction = .55 (helo)62 (tiltrotor)	30% reduction	
Cruise Speed	Helicopter = 170 kts	200 kts	
	Tiltrotor = 250 kts	Advanced Config. = 350 - 400 kts	
External Noise	External noise metric TBD	Below annoyance threshold	
Vibration & Internal Noise	.05g vibration	Imperceptible (.005g)	
Intelligent Automation & Cockpit Integration	Pilot aiding	Operator "directs" vehicle	
	Autonomous flight (UAV)	Autonomous mission optimization	
Reliability & Safety	Reliability metric TBD	Equivalent to fixed-wing airliners	
	Accident rate comparable to General Aviation	Equivalent to fixed-wing airliners	
All-Weather Operability	IFR-capable	Fully autonomous zero-zero	
	Limited icing capability	No restrictions due to icing	



## Advanced Rotor/Drive System Concepts

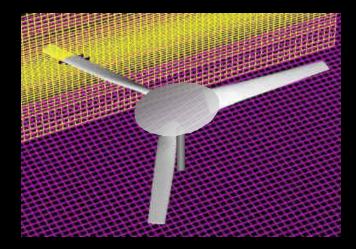
## Continuous control of shape and airflow achieves near-ideal performance

Smart material "morphing" blade geometry

Active blowing and boundary layer modification

Swashplate-less control

Lightweight rotor construction



Active vibration and noise control

Low-noise geometry

Super-safe rotor and drive shaft

Reverse velocity airfoils

Variable speed, intelligent, selfreconfigurable drive system



## Bio-Analogous Distributed Systems

Distributed sensors, processors, and actuation devices tailor drag and lift, counter vibration, diagnose faults, and implement corrective action

Active aerodynamic controls

Intelligent operator interface



Distributed sensors, processors, and actuation devices

Self-monitoring, adaptive, reconfigurable, self-healing systems



## Advanced Vehicle Configurations

High speed enhances productivity of piloted and uninhabited rotorcraft











# Personal Transport "Crashproof" Rotorcraft

UAV technology and smart systems enhance safety and reliability

## Environmentally friendly

Low-noise rotor

#### **Economical**

- Low-cost construction
- Affordable propulsion system



#### Safe and easy to operate

- Smart autonomous self-reconfigurable control system
- Super-safe health & usage monitoring and advanced diagnostics



## High Payoff Research Topics Have Robust Potential

#### **INNOVATIVE TECHNOLOGIES**

Intelligent Rotorcraft Systems	Efficient Active Rotor	Revolutionary Configurations
x	x	x
Х	x	х
х	x	х
х	x	х
х		Х
х	Х	х
x		Primary influence
	X  X  X  X  X  X	X X X X X X X X X X X X X X X X X X X



### Conclusions

- Meeting 21st Century air transport needs represents a significant growth opportunity for the rotorcraft community
- Rotorcraft can play a key role in the air transportation system of the future ...
- > ... if they can achieve competitive ticket cost, community acceptance, and passenger comfort
- Rotorcraft have improved on many fronts, but the technology is still maturing
- A strong research effort will be needed to meet NASA, DoD, and industry goals